

COMPUTER-AIDED DESIGN COURSE WITH MATLAB



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Computer-Aided Design Course

Course description and learning objectives

- Offered every spring semester
- Undergraduate level senior (4th year) students
- Mechanical Engineering
- Physical

Learning objectives:

- To introduce fundamental technologies underlying Computer-Aided Design (CAD) and implementing in MATLAB.
 - To show how they can be used to aid engineering design, not just the geometry documentation.
- To provide an open classroom where students can learn by doing,
 - To relate the course material to their research and experience.

Computer-Aided Design Course

Reason for adoption MATLAB

- To teach the computer-aided design (CAD) fundamentals by implementing them in MATLAB.
- The topics are as follows:
 - 1) Primitive Instance Modeling
 - 2) Rigid Body Transformations (Scaling, Translation, and Rotation of Models)
 - 3) Curve and Surface Modeling
 - 4) Topology Optimization
 - 5) CAD to Additive Manufacturing (3D Printing)

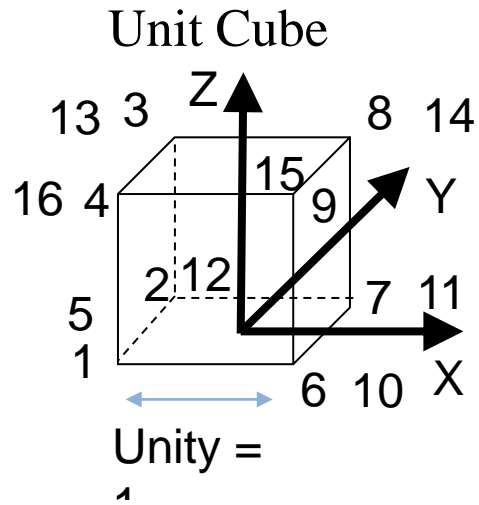
How MATLAB and Simulink were used in the course

MATLAB is used in class practices and additional activities:

- 5 Homework Assignments (35% of grade)
 - Significant Matlab programming is required: part modeling, curve and surface modeling, topology optimization.
- A Final Project based on MATLAB programming (35% grade)
 - Select projects and groups based on your interests and/or research.
 - Topology Optimization + Surface modeling + STL model conversion + 3D printing in MATLAB

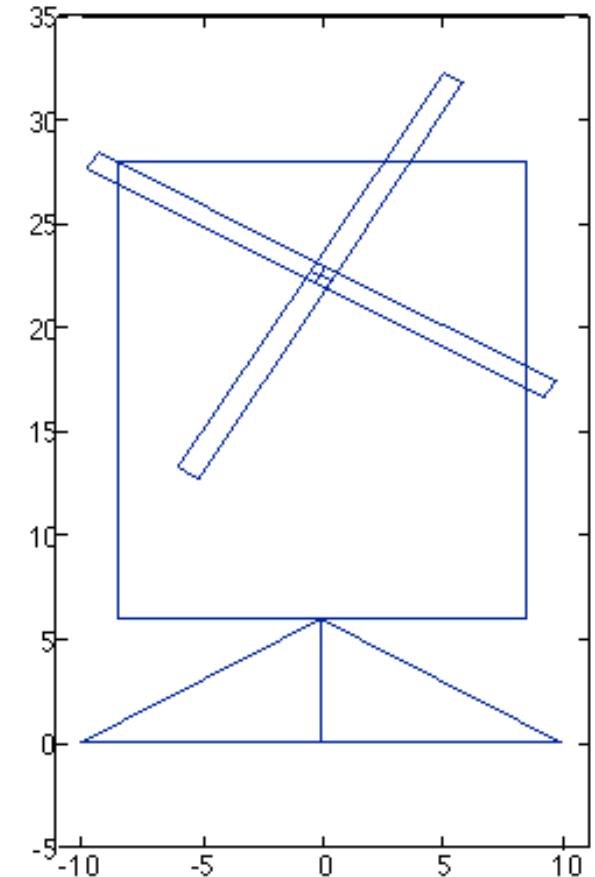
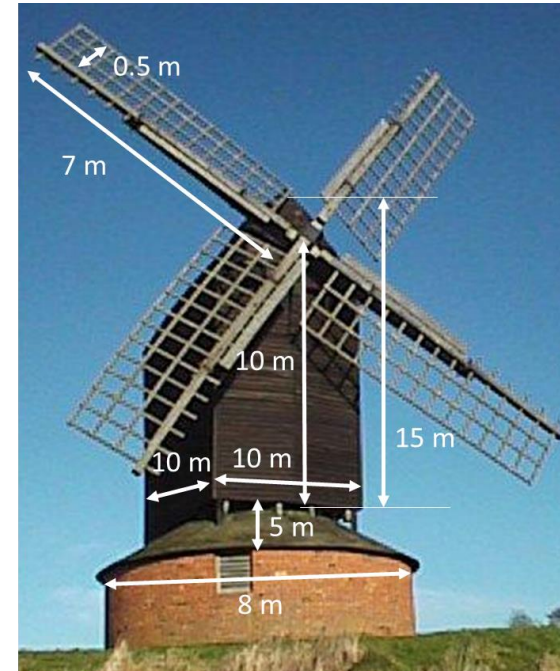
1) PRIMITIVE INSTANCE MODELING IN MATLAB

- Learning primitive instancing (creating simple shapes) and MATLAB
- Primitives = simple shapes
- Instancing = creating a primitive
- Learn how to plot graphs in MATLAB starting by plotting a simple cube.



```
Cube = [-0.5, -0.5, -0.5, -0.5, -0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 0.5, -0.5, -0.5, 0.5, 0.5, -0.5;
0, 0, 1, 1, 0, 0, 0, 1, 1, 0, 0, 0, 1, 1, 1, 1;
-0.5, 0.5, 0.5, -0.5, -0.5, -0.5, 0.5, 0.5, -0.5, -0.5, 0.5, 0.5, 0.5, 0.5, -0.5, -0.5;
1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1];
```

Plotting a wind mill in MATLAB using primitive instances.

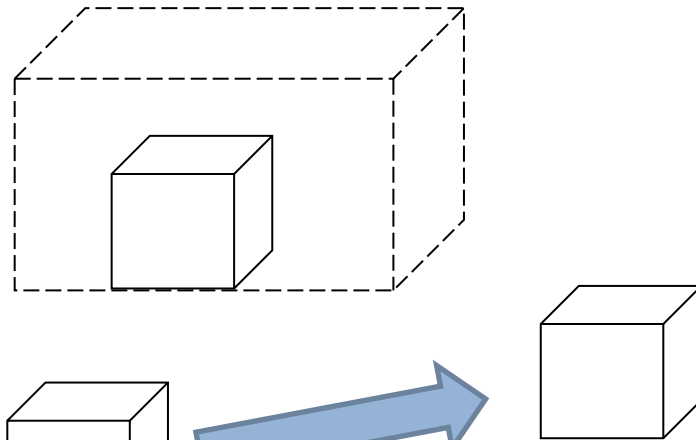


2) RIGID BODY TRANSFORMATIONS

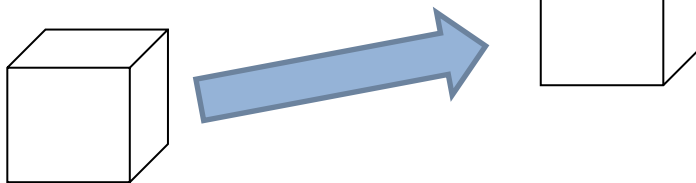
- Describe relative motion among parts in an assembly.
- Size, position and orient features in a part (rigid body transformations).
- Describe CAD model views.
- Apply rigid body transformations in MATLAB in a wind mill example and in a homework assignment

3 OPERATIONS:

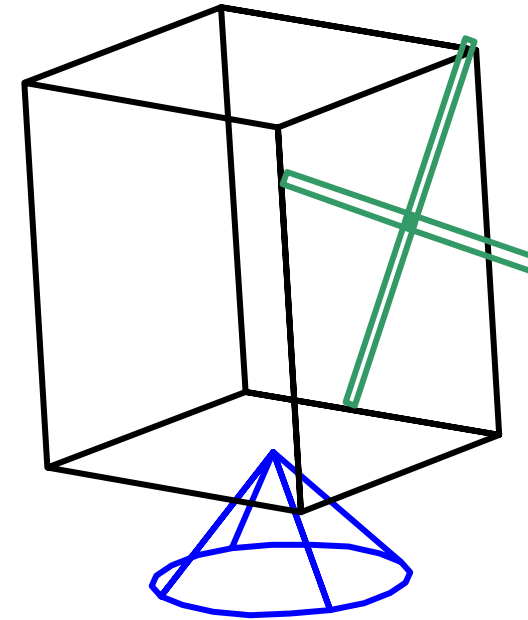
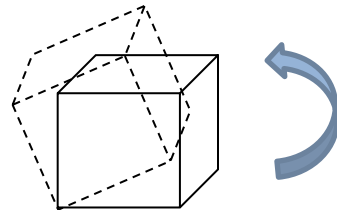
1) SCALING:



2) TRANSLATION:



3) ROTATION:

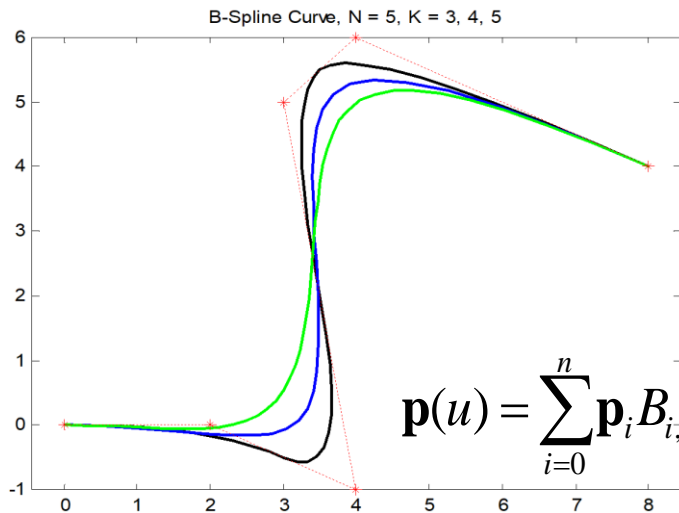


3) CURVE AND SURFACE MODELING

- Parametric Curves

- Hermite Curves
- Bezier Curves
- B-spline Curves
- NURBS

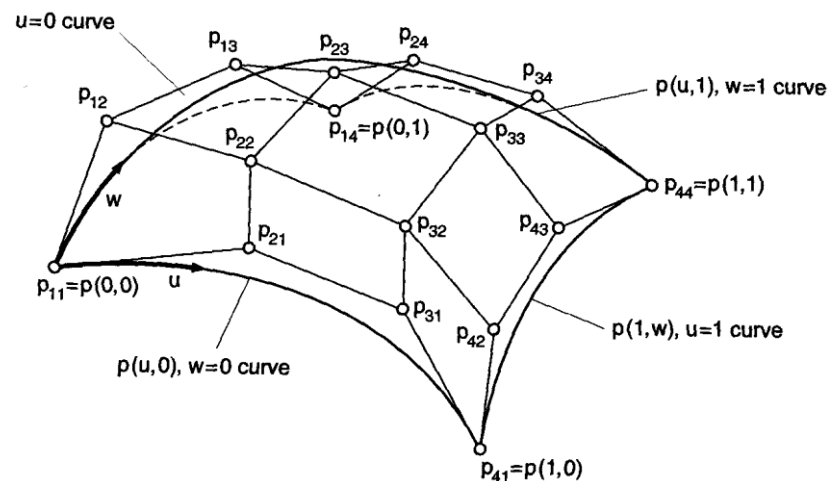
- A homework assignment to apply them in MATLAB



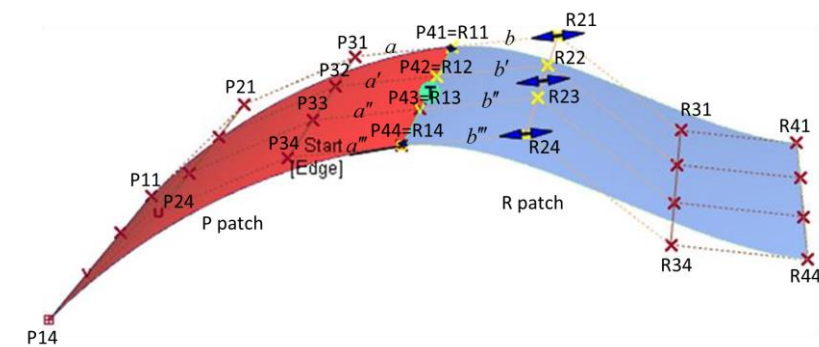
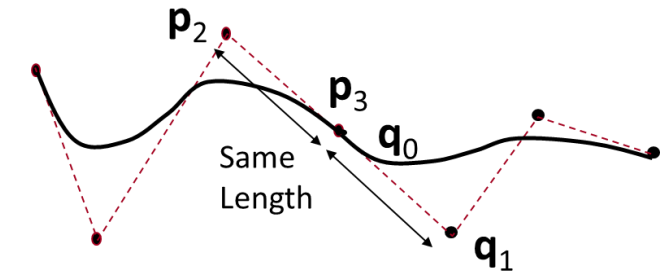
- Parametric Surfaces

- Hermite Curves
- Bezier Curves
- A homework assignment to apply them in MATLAB

$$p(u, w) = \sum_{i=0}^m \sum_{j=0}^n p_{ij} B_{i,m}(u) B_{j,n}(w)$$

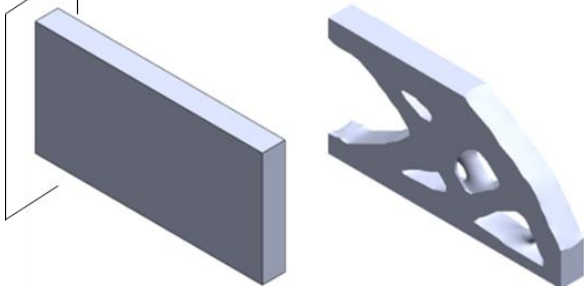


- Continuity in Curves and Surfaces



4) TOPOLOGY OPTIMIZATION

Removing material from an initial layout



Compliance minimization

Compliance \leftarrow Displacement Vector \leftarrow Stiffness matrix

$$\min : C = \sum_{i=1}^n u_i^T k_i u_i$$

Subject to: $V(\rho) - f V_0 \leq 0$
 $; KU = F \rightarrow$
 $; 0 < \rho_{min} \leq \rho \leq 1$

$V(\rho)$: Optimized Volume
 f : Volume fraction
 V_0 : Initial total volume
 F : Force vector

$$k_i(\rho_i) = \int_{-1}^{+1} \int_{-1}^{+1} \int_{-1}^{+1} \mathbf{B}^T \mathbf{C}_i(\rho_i) \mathbf{B} d\xi_1 d\xi_2 d\xi_3$$

Solid Isotropic Material Penalization (SIMP)

$$E_i = E_0 \rho_i^p$$

$$C_i(\rho_i) = E_i(\rho_i) C_i^0$$

For isotropic material

$$C_i^0 = \frac{1}{(1+\nu)(1-2\nu)} \times \begin{bmatrix} 1-\nu & \nu & \nu & 0 & 0 & 0 \\ \nu & 1-\nu & \nu & 0 & 0 & 0 \\ \nu & \nu & 1-\nu & 0 & 0 & 0 \\ 0 & 0 & 0 & (1-2\nu)/2 & 0 & 0 \\ 0 & 0 & 0 & 0 & (1-2\nu)/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & (1-2\nu)/2 \end{bmatrix}$$

OPTIMIZATION ALGORITHM

Optimality Criteria:

A gradient-based algorithm. Recall update scheme:

$$\mathbf{X}^{k+1} = \mathbf{X}^k - \alpha \nabla f^k(\mathbf{X})$$

A heuristic update scheme is used in Optimality Criteria Method:

Method:

$$x_e^{\text{new}} = \begin{cases} \max(0, x_e - m) & \text{if } x_e B_e^\eta \leq \max(0, x_e - m) \\ \min(1, x_e + m) & \text{if } x_e B_e^\eta \geq \min(1, x_e + m) \\ x_e B_e^\eta & \text{otherwise} \end{cases} \quad \begin{array}{l} m=0.2, \eta=0.5 \\ \text{is} \\ \text{recommended} \end{array}$$

B_e are obtained from the optimality condition defined by the derivatives:

$$\frac{\partial c(\tilde{\mathbf{x}})}{\partial x_e} + \lambda \frac{\partial v(\tilde{\mathbf{x}})}{\partial x_e} = 0 \Rightarrow B_e = \frac{-\frac{\partial c}{\partial x_e}}{\lambda \frac{\partial V}{\partial x_e}} \begin{array}{l} \xrightarrow{\text{top}} \frac{\partial c}{\partial x_e} = -p x_e^{p-1} (E_0 - E_{\min}) \mathbf{u}_e^T \mathbf{k}_0 \mathbf{u} \\ \xrightarrow{\text{bottom}} \frac{\partial V}{\partial x_e} = v_e = 1 \text{ for unit volume elements} \end{array}$$

λ is the lagrange multiplier.

It is determined by the bisection algorithm such that it satisfies the volume constraint:

$$\lambda = 0.5 * (l_2 + l_1) \quad \text{Initially } l_1 = 0; l_2 = 1e9$$

Stops when $(l_2 - l_1) / (l_1 + l_2) > 1e-3$

$l_1 = \lambda$ if Vol constraint is not satisfied.

$l_2 = \lambda$ if Vol constraint is satisfied.

MATLAB CODES FOR TOPOLOGY OPTIMIZATION

<http://www.topopt.dtu.dk/>

Software produced by the Technical University of Denmark

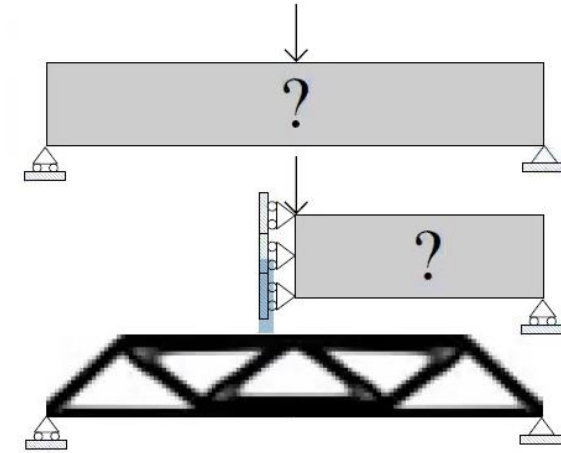
- They offer software for free download.
- Good summary and many examples
- Provides also 2D/3D computer code that we will analyze.
- Can get also a mobile phone ap that would do for you topology optimization.
- Exercise: Use the top ap or the web site to design a bar in tension with aspect ratio of 3, with the tensile loads applied at two corners of the rectangle.

[top3d](#)

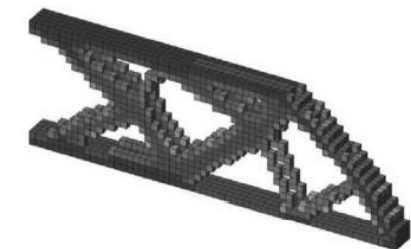
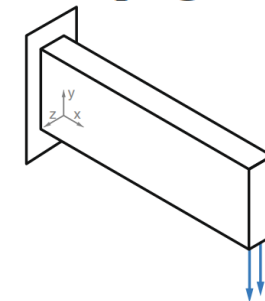
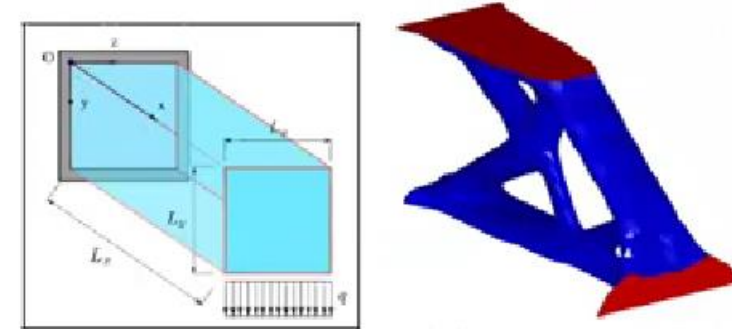
Top3d is a **free** MATLAB[®] program that solves topology optimization problem in 3D. The program is:

- compact without sacrificing readability,
- easy-to-use without losing complexity, and
- multi-functional without programming immensity.

2D topology optimization code



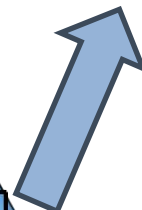
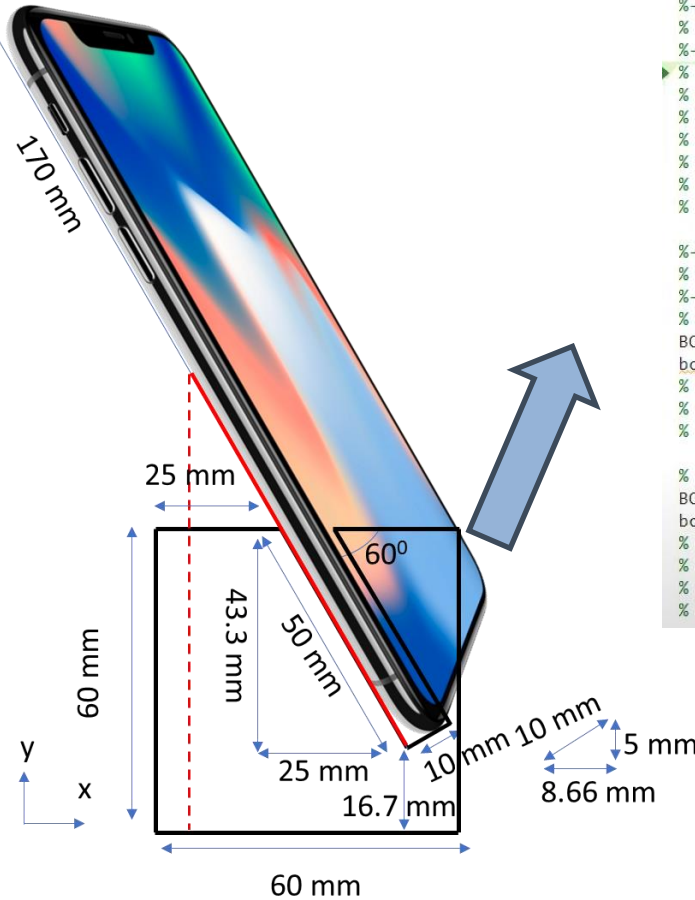
3D topology optimization code



HOMWORK ASSIGNMENT FOR TOPOLOGY OPTIMIZATION

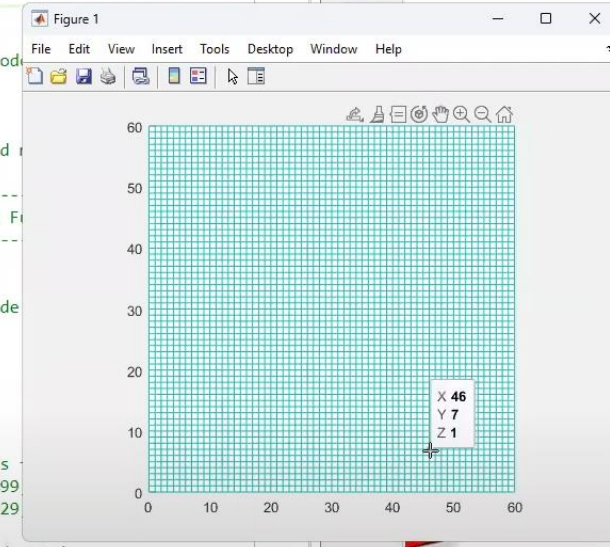
Initial domain discretization and loadings in MATLAB

- Phone stand design



```

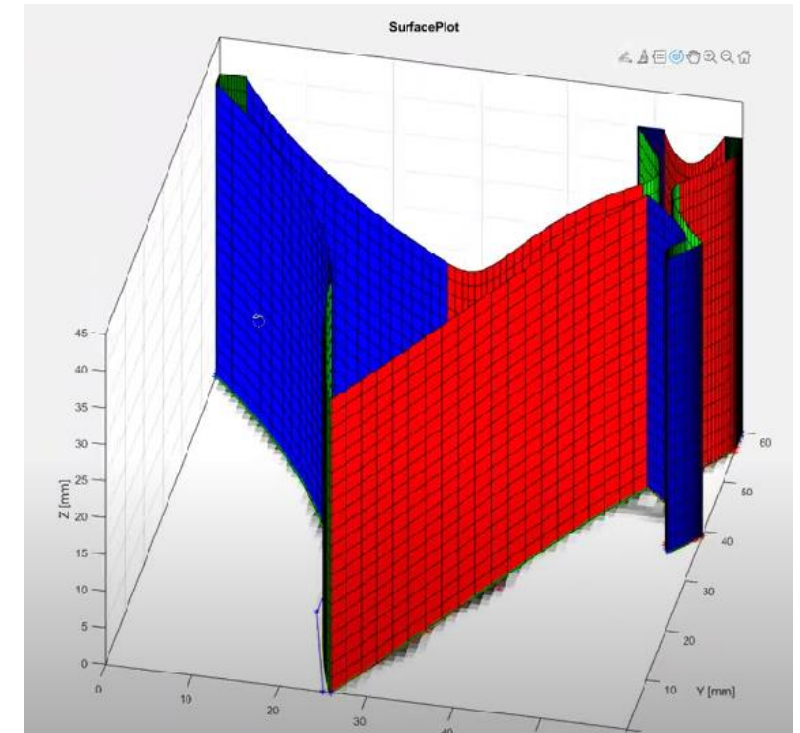
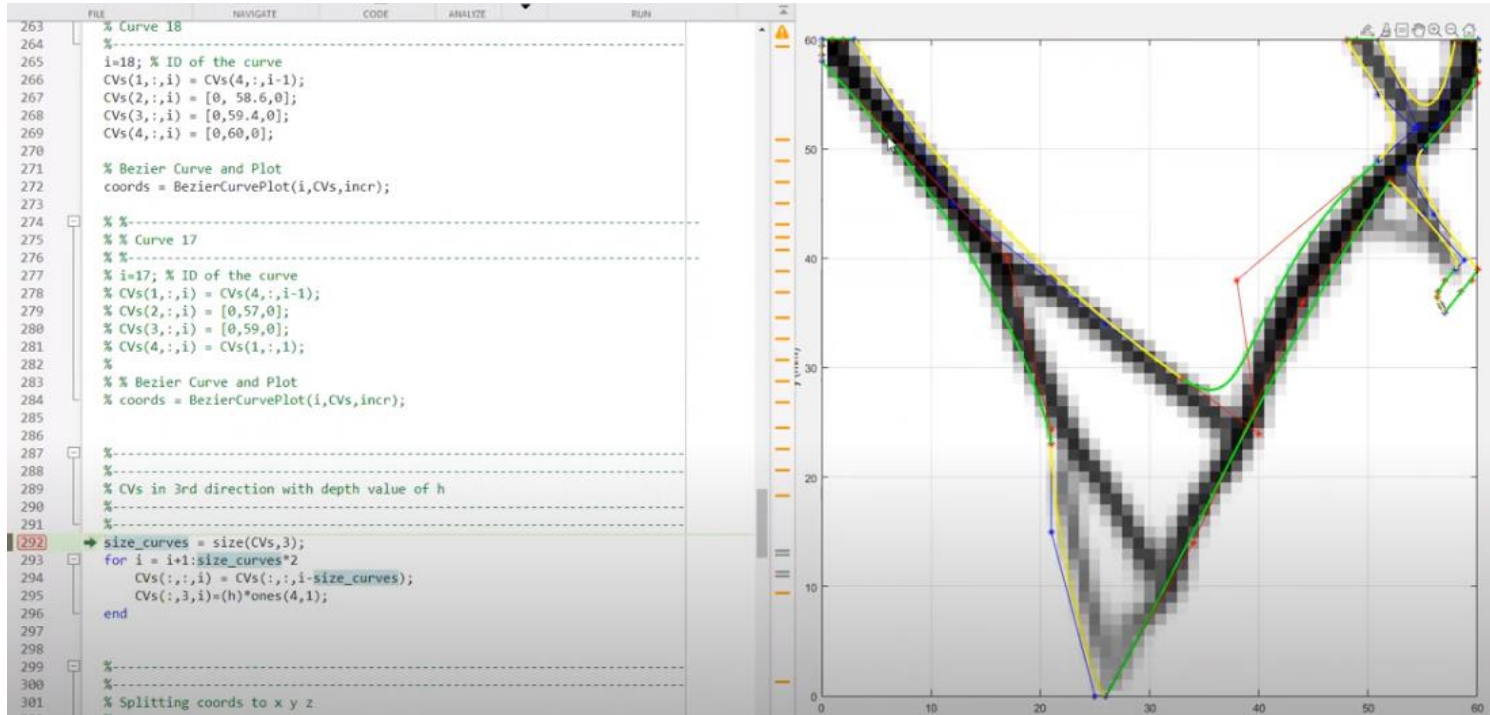
%-----
% BCs and LCs for the MBB beam example in the paper
%-----
% BCnode = nodeNrs(:,1)';
% bc = [2*BCnode-1 2*nodeNrs( end, end )];
% % bc_old = union( 1 : 2 : 2*( nely + 1 ), 2 * nodeNrs( end, end ) );
%
% Fnode = nodeNrs( 1, 1 );
% lcDof = 2*Fnode; % DOF to apply load
% F = fsparse( lcDof', 1, -1, [ nDof, 1 ] ); %Load matrix
%-----
% BCs and LCs for the bracket example in Autodesk FEA
%-----
% One node BC and LC
BCnode = [61, 3721];
bc = [2*BCnode-1, 2*BCnode]; % 2 DOFs for each node
Fnode = [6841];
lcDof = 2*Fnode;
F = fsparse( lcDof', 1, -1, [ nDof, 1 ] );
%-----
% Multiple Load BCs and LC
BCnode = nodeNrs(end,:);
bc = [2*BCnode-1, 2*BCnode]; % DOFs to fix (2 DOFs)
Fnode = [6841, 6784, 6727, 6670, 6613, 6556, 6499,
        6271, 6214, 6157, 6100, 6043, 5986, 5929];
lcDof = 2*Fnode; % DOF to apply load
F = fsparse( lcDof', 1, -1, [ nDof, 1 ] ); %Load matrix
    
```



BEZIER CURVE AND SURFACE MODELING OF OPTIMIZED DESIGN

Bezier curve MATLAB function is used with continuities to define the geometry boundaries using the topology optimization image

The curves are converted to lofts Bezier surfaces in MATLAB to have a 3D model:

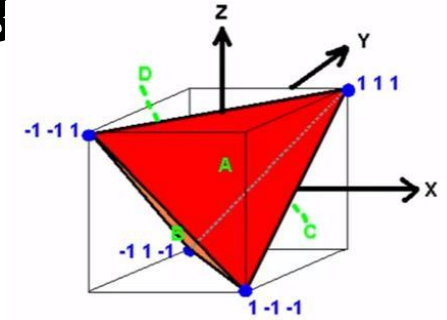


5) MODELING FOR ADDITIVE MANUFACTURING

CAD to Additive Manufacturing



STL format and generation in MATLAB



```

solid tetrahedron
facet normal 0 0 0
outer loop
vertex 1 1 1
vertex 1 -1 -1
vertex -1 -1 -1
endloop
endfacet
facet normal 0 0 0
outer loop
vertex 1 1 1
vertex -1 1 -1
vertex -1 -1 1
endloop
endfacet

```

```

facet normal 0 0 0
outer loop
vertex 1 1 1
vertex -1 -1 1
vertex 1 -1 -1
endloop
endfacet
facet normal 0 0 0
outer loop
vertex -1 1 -1
vertex 1 -1 -1
vertex -1 -1 1
endloop
endfacet
endsolid tetrahedron

```

PHONE STAND EXAMPLE FOR STL GENERATION AND 3D PRINTING

MATLAB code for STL Generation from Bezier Surface

```

%Write each surface to STL
str1 = 'Surface';
str2 = '.stl';
for i = 1:size(CVx,3)
    str3 = num2str(i);
    surf2stl(strcat(str1,str3,str2),Px(:,:,i) ,Py(:,:,i) ,Pz(:,:,i));
end

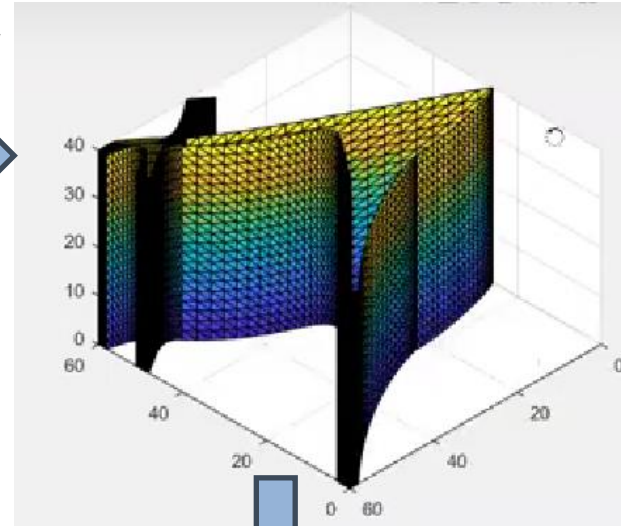
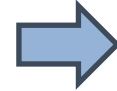
%Read All STLs
for i = 1:size(CVx,3)
    str3 = num2str(i);
    fv(:,:,i) = stlread(strcat(str1,str3,str2));
end

%Merge All STLs
fvmerged = stlmerge(fv(:,:,1),fv(:,:,2));
for i = 3:size(CVx,3)
    str3 = num2str(i);
    fvmerged = stlmerge(fvmerged,fv(:,:,i));
end

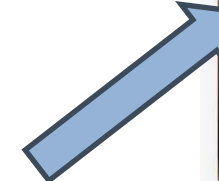
%Write the final STL file
stlwrite('Model_Main.stl',fvmerged)

%Plot the STL model
data = stlread('Model_Main.stl');
stlPlot(data.vertices, data.faces, 'sonuc')
h=plotmesh(data.vertices,data.faces);

%Delete surface patch STL files
for i = 1:size(CVx,3)
    str3 = num2str(i);
    namestl = strcat(str1,str3,str2);
    delete (namestl)
end
    
```



Using a free 3D printing software (Prusa Slicer) to create g-code for 3D printing from the STL file.



FINAL PROJECT FLOW CHART

**3D Topology Optimization
in MATLAB**

+

**3D Parametric Surface
Modeling in MATLAB**

+

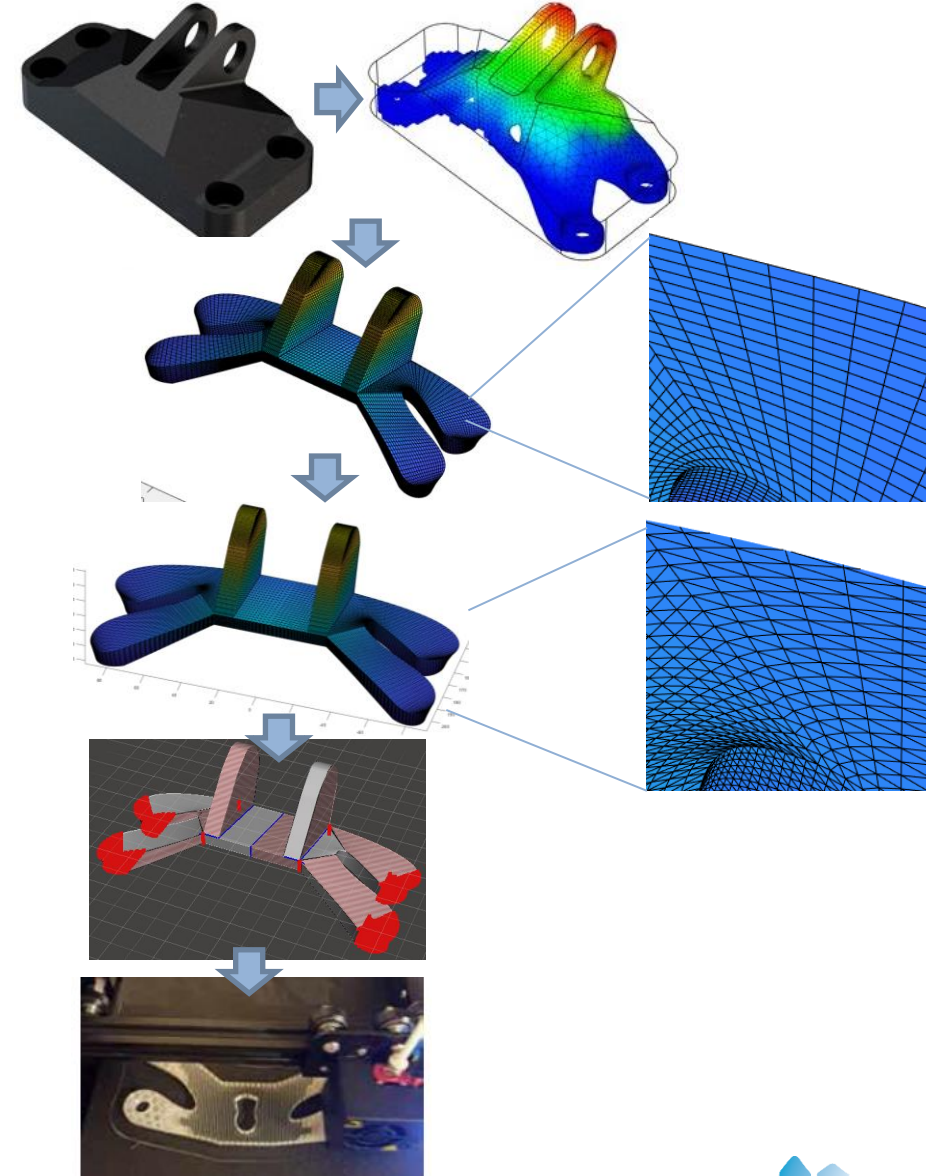
**STL Model Conversion in
MATLAB**

+

**STL Repair in 3rd party
software (if necessary)**

+

Slicing and 3D printing



Benefits / added value of using MATLAB and Simulink

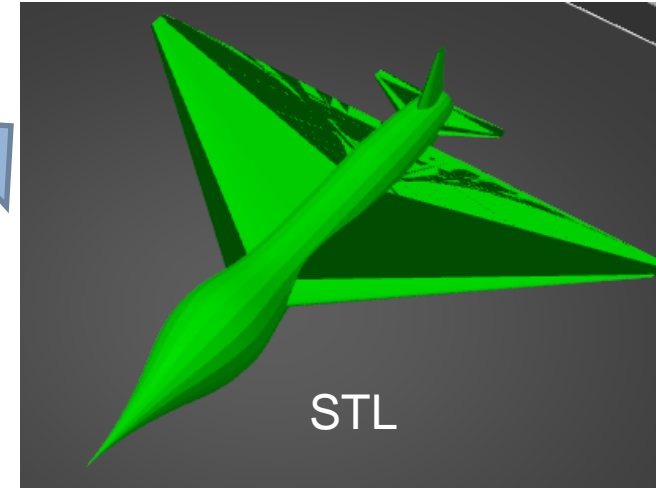
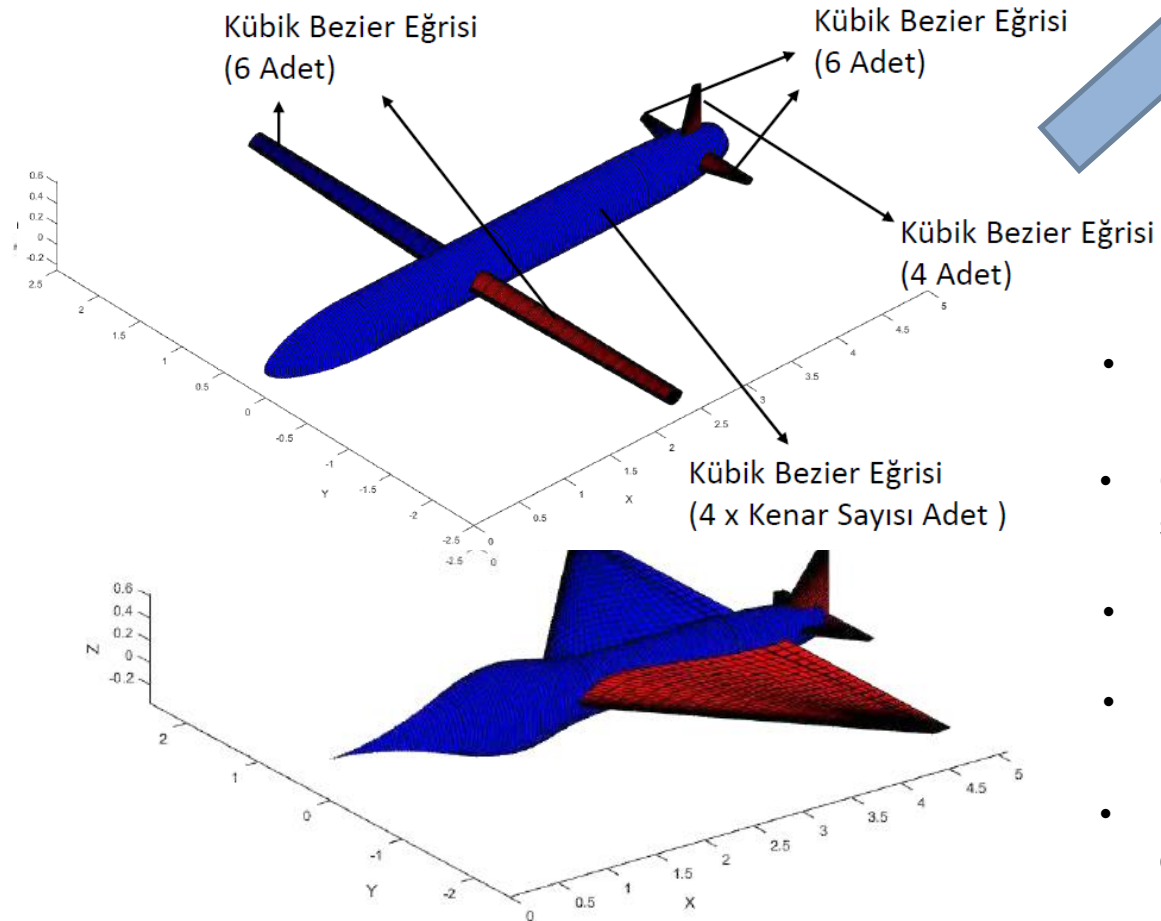
- Students learn CAD Fundamentals by applying.
 - Primitive Instancing
 - Curve and Surface Modeling
 - Topology Optimization
 - CAD to Additive Manufacturing

- New project / design / coding ideas are developed in different disciplines (e.g. Aerospace, biomedical, consumables, etc).

- Customized CAD programs are developed in MATLAB.

- Some examples are given in the following slides.

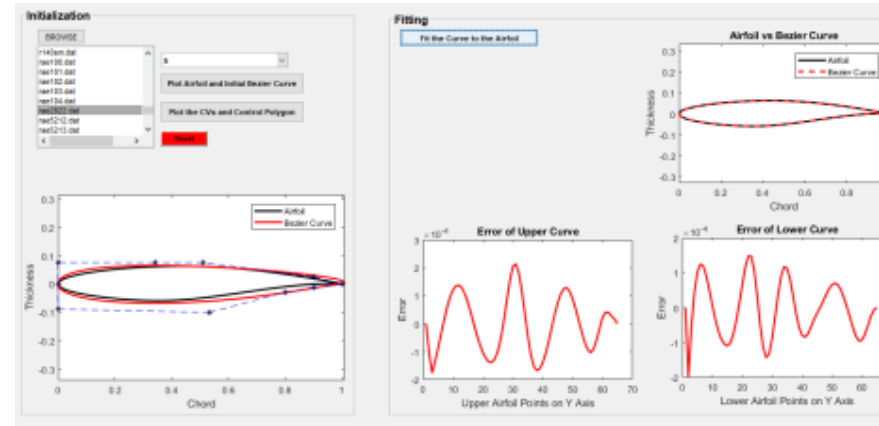
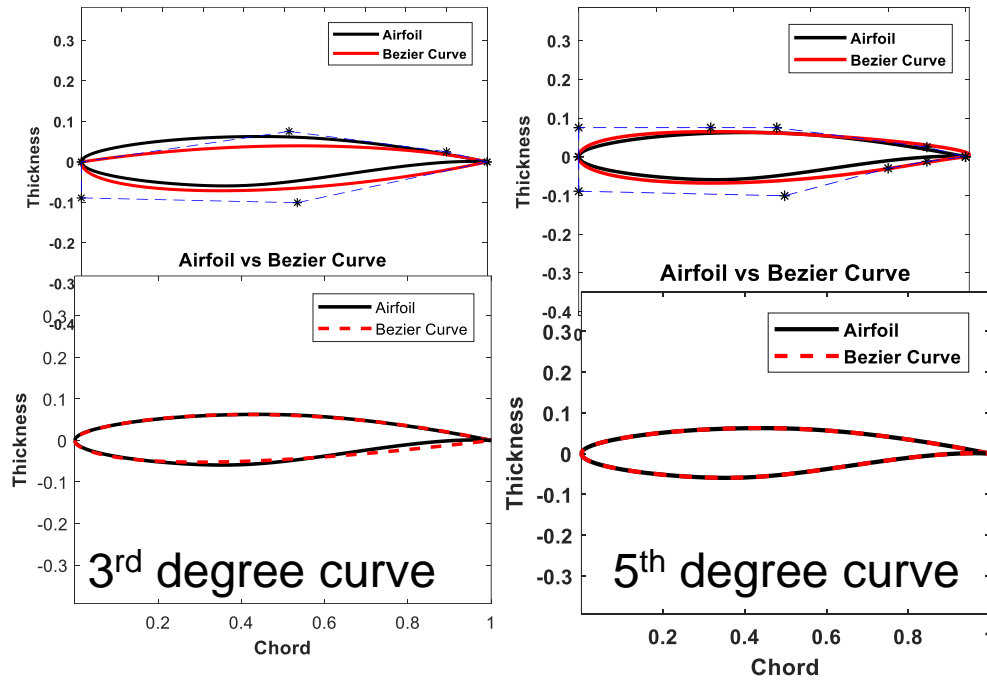
Example 1: Unmanned Aerial Vehicle Design Tool in MATLAB



- Converting each surface by “surf2stl.m” to an STL file.
- Open each STL in .txt format and delete the final rows starting with “endsolid”.
- Add all texts in all these STL files together.
- Add a row of “endsolid” to the end of the text and save as STL extension.
- Repair the STL file in a free software such as Netfabb or meshmixer if necessary.

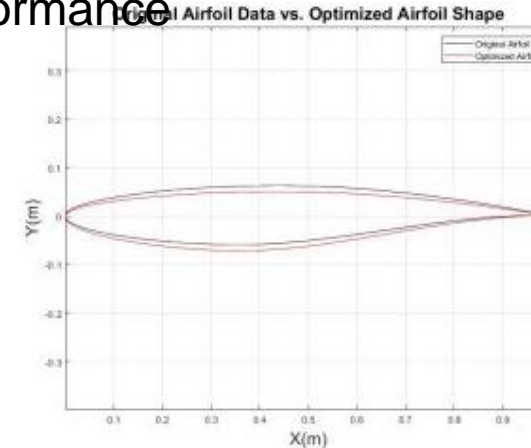
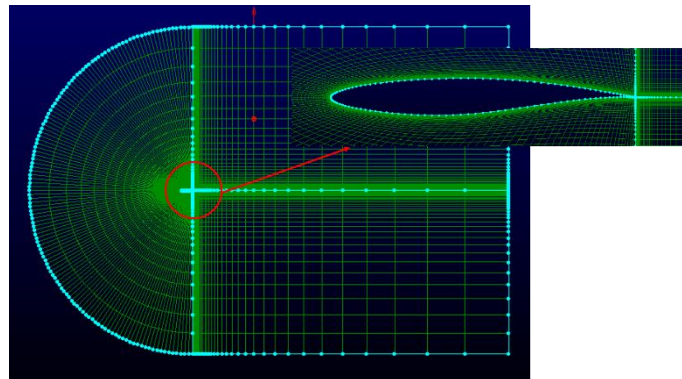
Example 2: Airfoil curve/surface fit

Parametric Curve Fitting to Airfoil Geometry in MATLAB



Optimal design for best performance

Mesh generation for flow analysis.



Example 3: Wing Design with Lattice Core

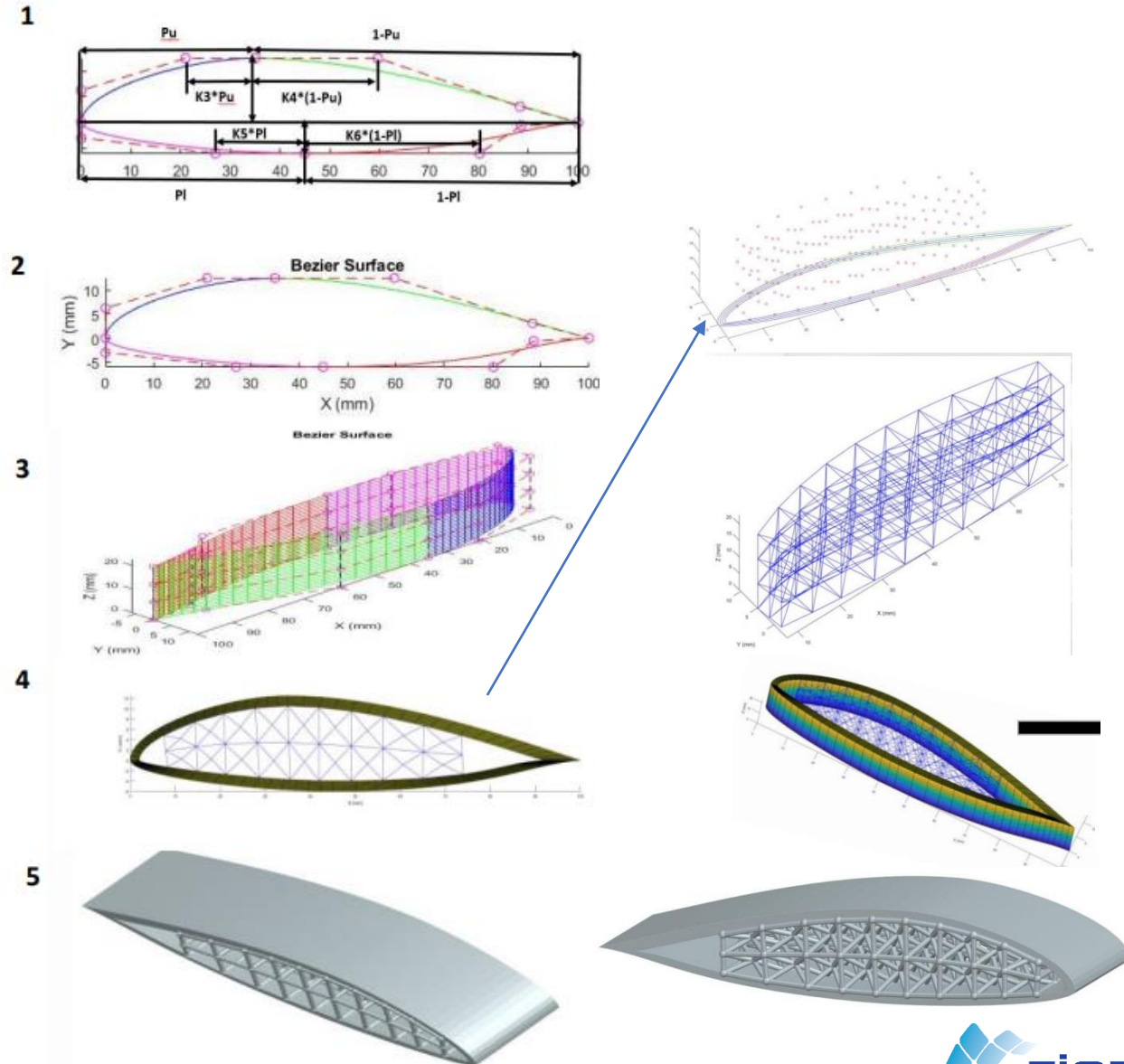
1. Identify wing profile parameters

2. Parametric modeling of airfoil using Bezier curves

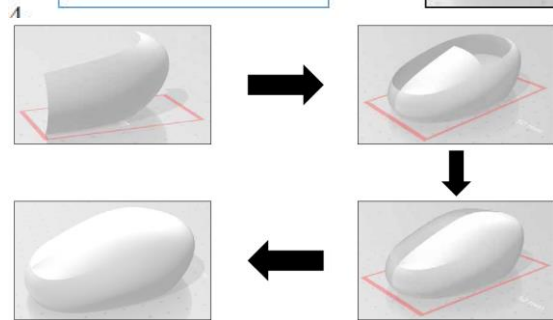
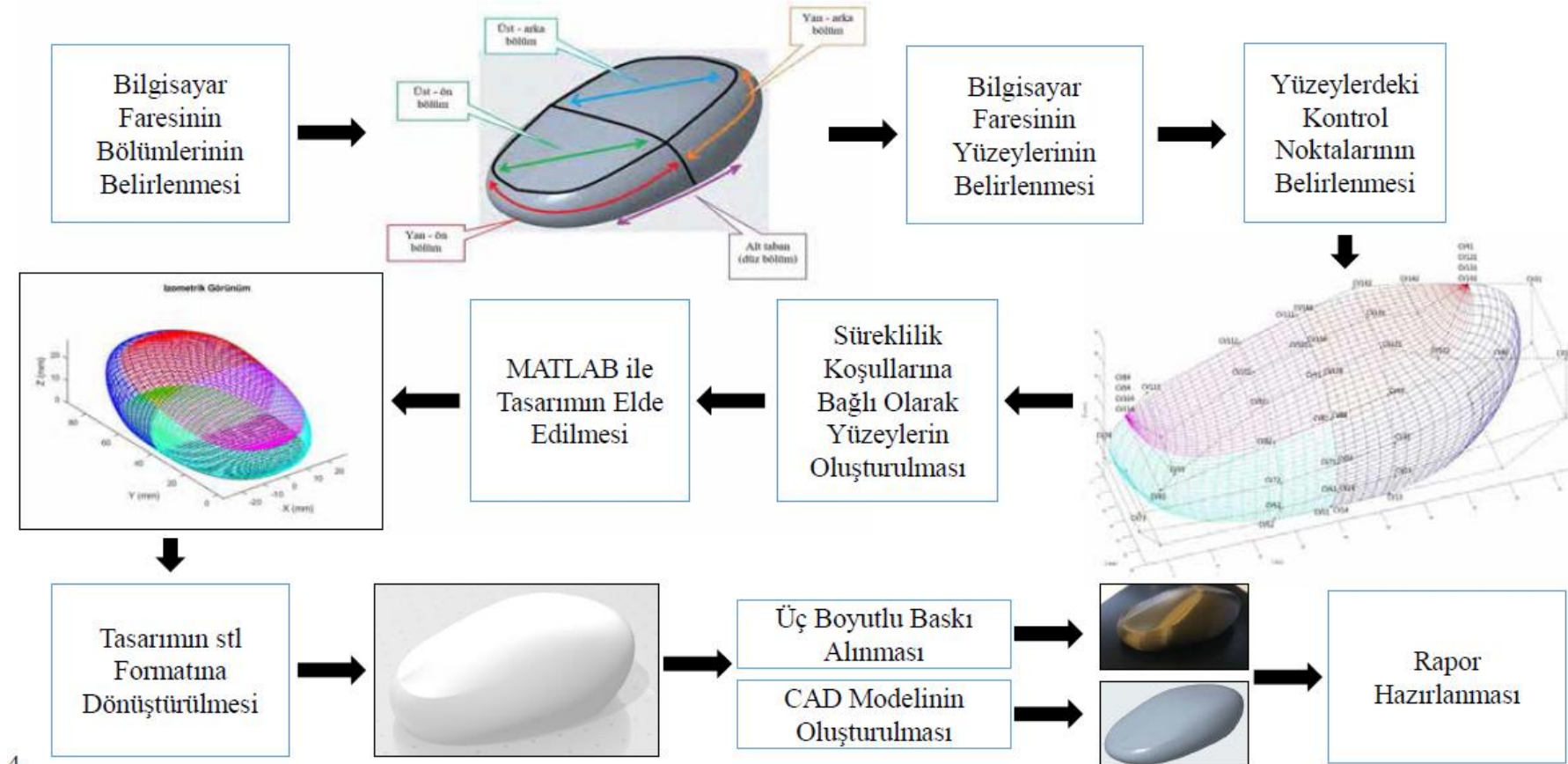
3. Parametric modeling of wing using Bezier surfaces

4. Placing lattice structure conformal to wing surface

5. STL model generation of the wing model.



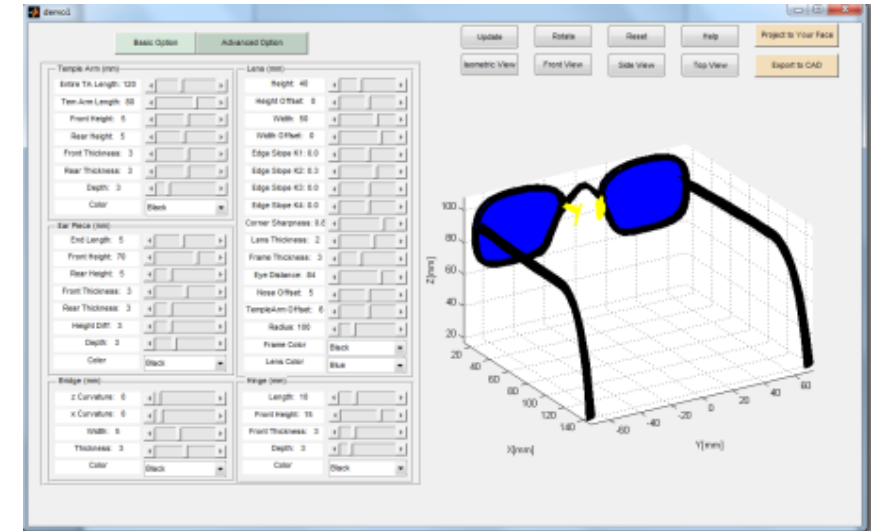
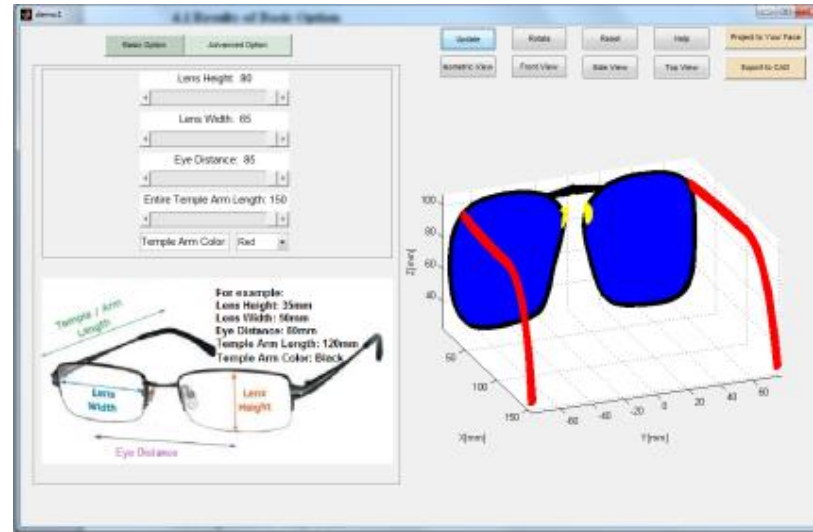
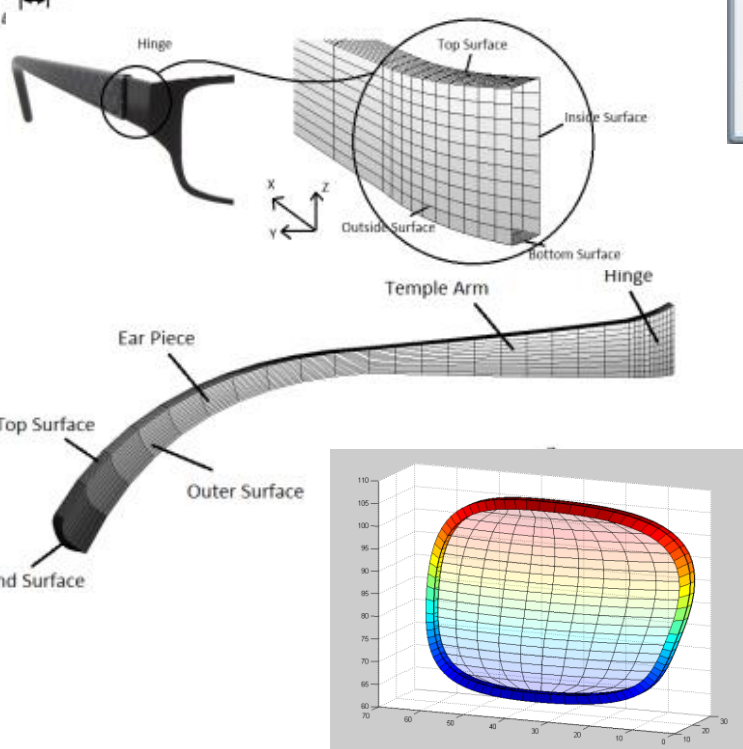
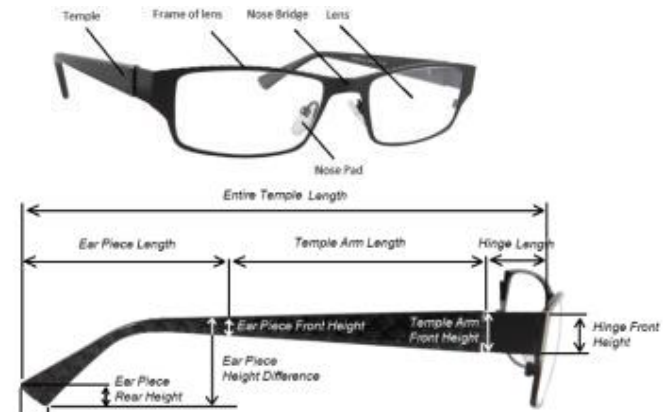
Example 4: Parametric Computer Mouse Design



- “surf2stl.m” function to create STL for each surface.
- “stlread.m” to read each STL file.
- “stlcombine.m” to combine each STL file read by MATLAB.
- “stlwrite.m” to write the combined STL file.
- Repair the STL file in Netfabb if necessary. Save as an STL file
- Slice the STL model in PrusaSlicer and generate the g-code for 3D printing.
- 3D print the model using the g-code in a 3D printer.

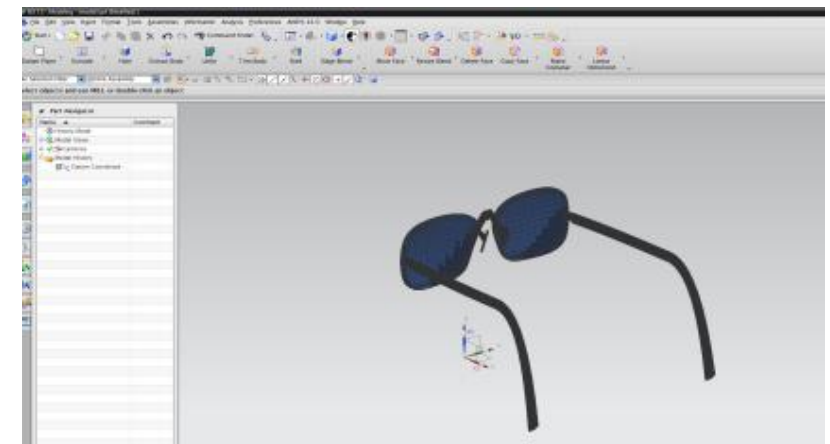
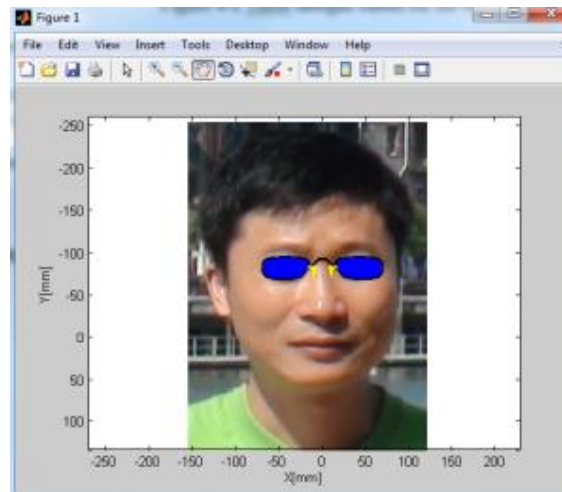
Example 5: Customized Eye Glass Design Tool

GUI in MATLAB for Parametric Eye Glass Modeling

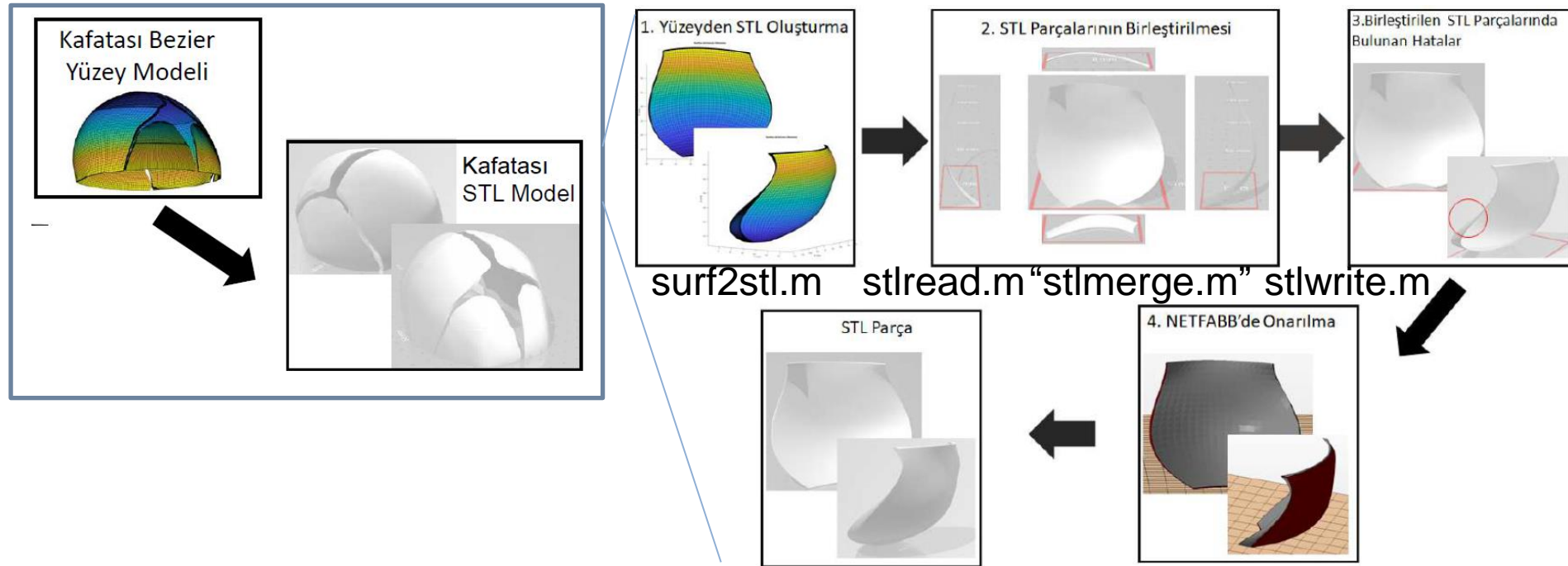


Projection to your face

Export to CAD system

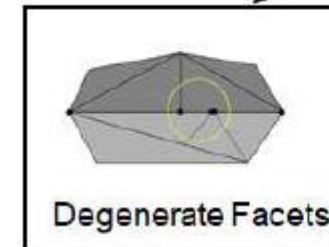


Example 6: Skull Modeling with Parametric Surfaces



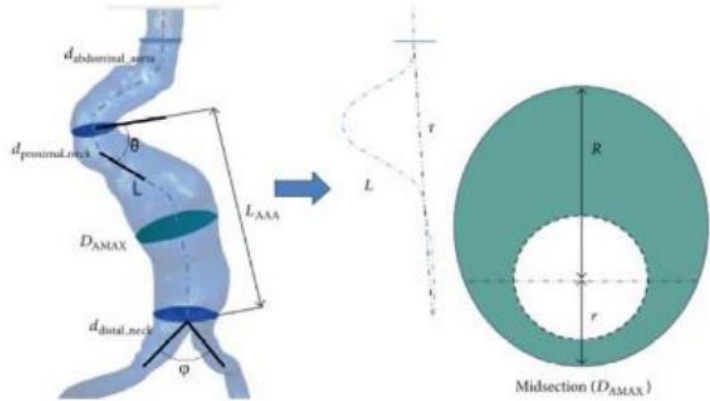
- “surf2stl.m” function to create STL for each surface.
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- 3D print the model using the g-code in a 3D printer.

STL Issues to be fixed in

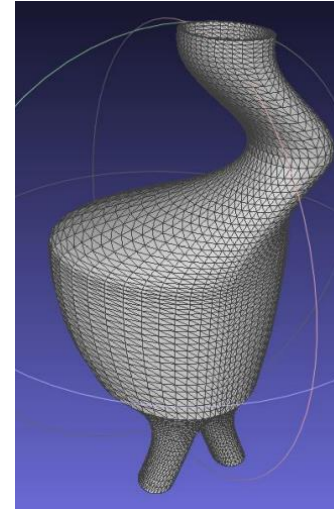


Example 7: Abdominal Aort Model

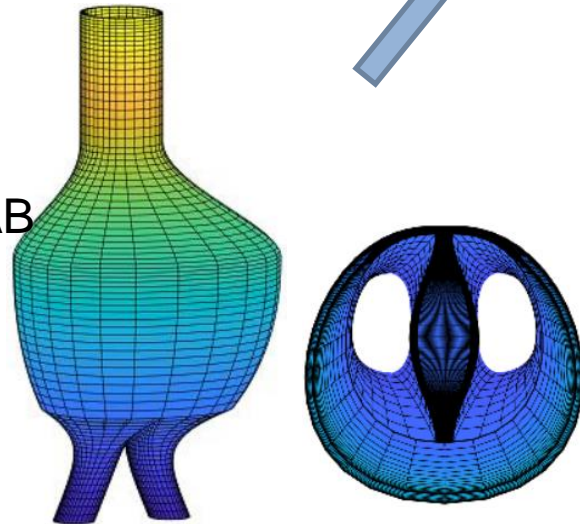
Parameterization of the geometry



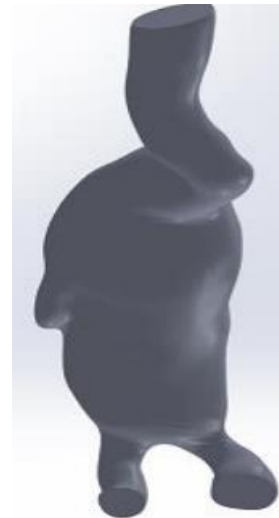
STL Model Generation In MATLAB



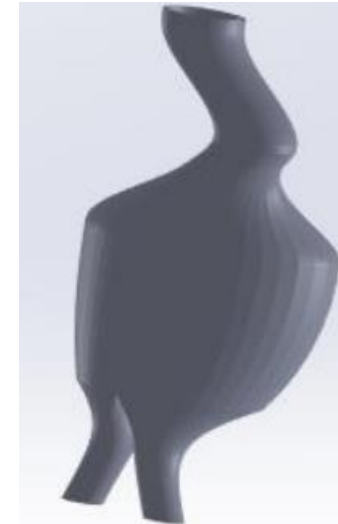
Bezier Surface Modeling in MATLAB



Actual Model

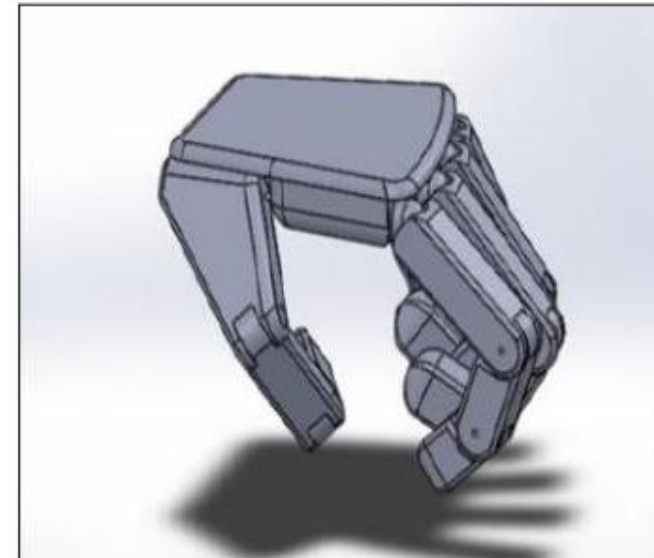
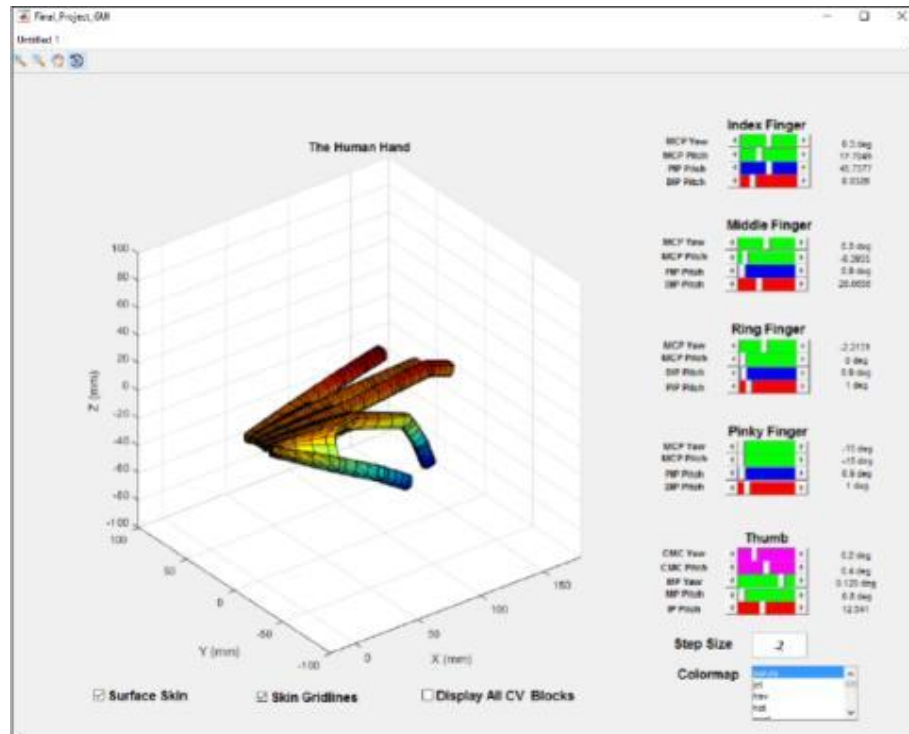
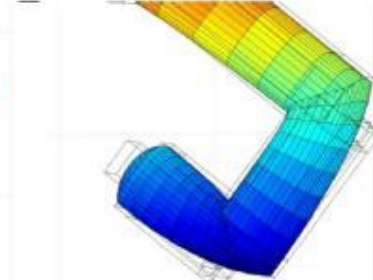
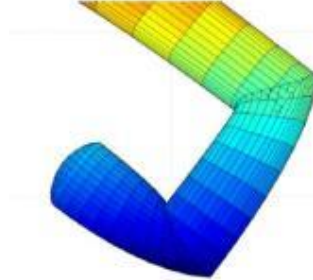
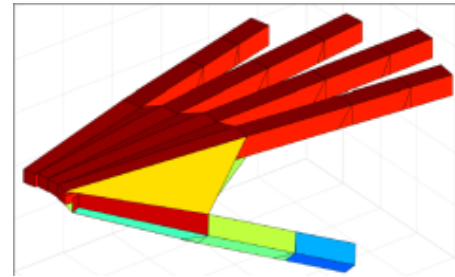
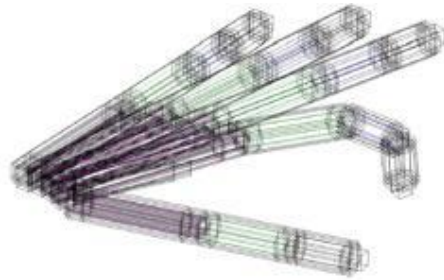


Surface Model



Example 8: Hand Design for Robotics

Parametric Robotic Hand Modeling in MATLAB

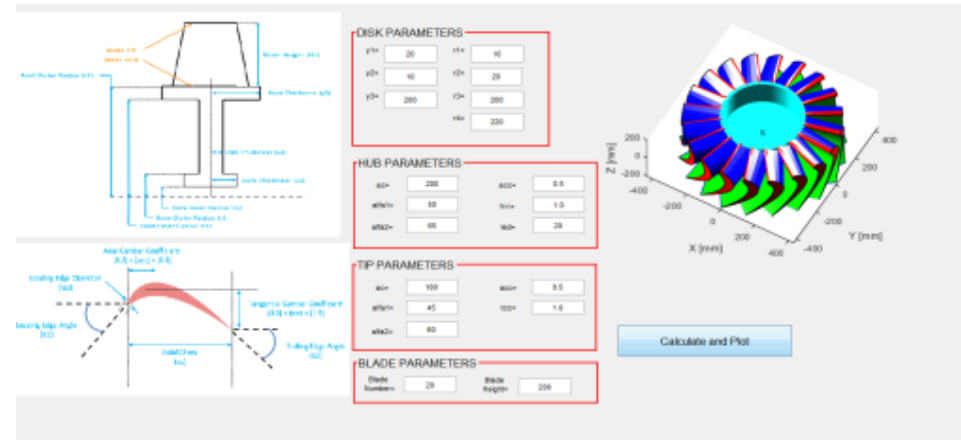


Other Examples

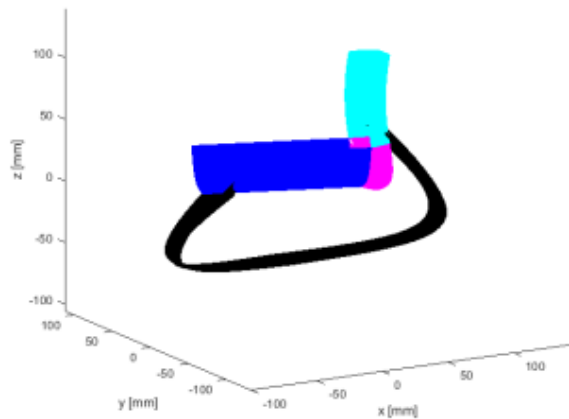
Internal Gear Design Optimization In MATLAB



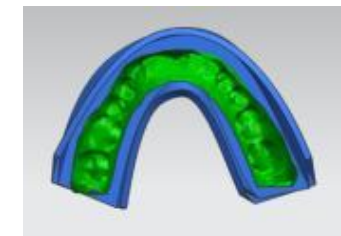
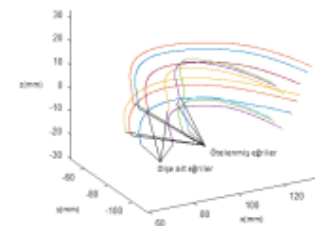
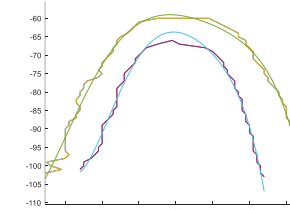
Planetary Gear Design in MATLAB



Leg Prosthesis Modeling for Animals



Parametric Mouthguard Modeling



Future plans

- CAD is an always developing area.
- Hence, new modeling and design optimization strategies can be added in the future.
- The course can also be opened in the graduate level.
- MATLAB Grader will also be integrated for grading the MATLAB assignments.

Thank you

Q&A – 5min

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